### RocFrac User's Guide

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# RocFrac Command Statements

The purpose of RocFrac is to simulate complex dynamic fracture problems using an explicit Cohesive Volumetric Finite Element (CVFE) scheme. RocFrac can handle large deformations, moving interfaces, and nonlinear material response.

#### 1.1 Compiling

The source files and makefile for the analysis code resides in the directory Rocfrac/Source in the GenX tree. The source files and makefile for the preprocessor *meshtran* reside in the directory Rocfrac/utilities/MeshTran. In order to compile *meshtran* you need to install the METIS package (http://www-users.cs.umn.edu/~karypis/metis/) and include a link to the *libmetis.a* file in the *Rocfrac/utilities/MeshTran* directory. The makefile for the utility *tetnhbor* can be found in Rocfrac/utilities/FindNeigh and is called *tetnhbor*.

### 1.2 Sequence Needed to Run a Problem

This section describes the sequence of execution needed in order to run RocFrac. In general, there are 4 steps involved: create the finite element mesh, partition the mesh and add cohesive elements (if required), solution and post-processing.

#### 1.2.1 Create Finite Element Mesh/Steps needed with Patran

The first step is to create the mesh. As of this writing there is only one practical way to create the volumetric tetrahedral mesh and that is to use the commercial package Patran. Please refer to the Patran documentation on how to use Patran for creating meshes. If Patran is used at NCSA then the user is limit to creating meshes no greater then roughly 1 million elements before needing to submit the Patran job as batch. Once the mesh and boundary conditions have been created the file needs to be exported to a Patran Neutral File. The file should have the same prefix as that found in the control deck file under the option **\*PREFIX**. The ending suffix of the neutral file must end in '.pat'.

#### 1.2.1.1 Geometry Creation

There are no special considerations to be address. The geometry can be created just as one would proceed to do for a finite element calculation.

#### 1.2.1.2 Mesh Creation

There are no special considerations that need to be taken when creating a finite element mesh, just engineering judgment. Note, however, that the only elements currently supported by Rocfrac is the 4 node and 10 node tetrahedral elements. Also, the use of both types of elements in modeling the geometry is not permitted. The entire mesh must be either 4 or 10 node elements.

#### 1.2.1.3 Boundary Condition Flags

The boundary conditions set in Patran are not the actual boundary conditions for the model, but instead represent flags that denote the actual boundary conditions.

#### Setting the Displacement Boundary Condition Flags

The way to set the boundary condition for the displacement boundary conditions is to assign the  $U_x$  fixed displacement the appropriate flag as that found in the control deck option **\*BOUNDARY** (See Section 2.1.16). For example, if the top of a specimen is to be fixed in all three directions then the  $U_x$  fixed displacement should be given a value of 1.0 in Patran, which will correspond to the boundary condition specified as card 1 under the **\*BOUNDARY** option.

#### 1.2. SEQUENCE NEEDED TO RUN A PROBLEM



Patran dialog box to set displacement boundary conditions

#### Setting the Mesh Motion Boundary Condition Flags

The way to set the boundary condition for the mesh motion boundary conditions is to use the 'create force dialog box' and assign the  $F_x$ fixed force the appropriate flag as that found in the control deck option **\*BOUNDARYMM** (See Section 2.1.17). For example, if the top of a specimen is to have fixed velocities in all three directions then the  $F_x$  fixed force should be given a value of 1.0 in Patran, which will correspond to the boundary condition specified as card 1 under the **\*BOUNDARYMM** option.

#### 1.2. SEQUENCE NEEDED TO RUN A PROBLEM

Action: Create 🖃	Load/BC Set Scale Factor
Object: Force 🖃	1.
Type: Nodal 💷	
Analysis Type: Structural — Current Load Case:	Force <f1 f2="" f3=""></f1>
Default	
Type: Static	
Existing Sets	y.
mm_fixedx mm_fixedxyz	Spatial Fields
New Set Name	
mm_fixedxyz	
	FEM Dependent Data
	Analysis Coordinate Frame
Input Data	
Select Application Region	OK Reset

# **1.2.2** Controlling what surface is in contact with the the fluids domain

To specify which surfaces are in contact with the fluids domain we use Patran's '*apply pressure*' dialog box. On the surfaces that are in contact with the fluid's domain we use a pressure value equal to 1. To specify the that a surface is not in contact with the fluid's domain we use a pressure value of 0.

#### 1.2. SEQUENCE NEEDED TO RUN A PROBLEM

Action:	Create 💷	Load/BC Set Scale Factor
Object:	Pressure 💷	1.
Type:	Element Uniform 🖃	
		Pressure
Analysis <sup>-</sup>	Type: Structural —	11.
Current L	oad Case:	
	Default	
Туре:	Static	
Existing	Sets	V
pressure	e_inner 🖉	Spatial Fields
-	d	
New Set	Name	
pressure	e side	2
		FEM Dependent Data
Target Ele	ement Type: 3D 💷	
	Input Data	
Calasia	un lingting Desire	OK Reset
Select A	Application Region	
	-Apply-	

### 1.2.3 Setting element flags

To specify the element flags using Patran for the volumetric flags we use the 'properties' option. Assign an element property to each volume where you want a different property. Note that you should not use the material property window.

— Element Properties 🕜 🗔				
Action:	ion: Create 🗕			
Object:	3D 🗆			
Туре:	Solid –	-		
Existing	Proper	ty Sets	_	
prop1 prop2 prop3				
Proper	ty Set N	lame		1
Option(	;):		,	
Standard Formulation 😐				
Input Properties				
Application Region				
Select Members				
Add Remove				
Application Region				
-Apply-				

#### 1.2.4 Run Meshtran

Once the Patran neutral file has been created, the program *tetnhbor* needs to be run in order to obtain each tetrahedra's neighboring elements. Again, the source code can be found in the Rocfrac/utilities/FindNeigh directory. The main subroutine was written by Tim Baker and all questions about the subroutine should be directed to him. The executable should be placed in the same directory as the Patran Neutral file. Execution is self-explanatory. The resulting file will be called pre-fix>.neigh.

The program Meshtran creates the cohesive elements (if needed) and partitions the mesh using the program METIS. It currently only supports the inclusion of cohesive elements everywhere in the domain. To run type: *MeshTran* in the same directory as the Patran output files. Execution is self-explanatory and two command line options are available; -np # tells Meshtran how many processors to partition the mesh and -un # (where # is the units conversion factor) which is useful to convert the units of the geometry. Meshtran will then create each processor's input file in the directory *Rocfrac/<prefix>* and each file will be called *<prefix>.###.inp* where *###* corresponds to the processor's id. It will also create the 2d interface mesh needed to be registered with RocCom via RocFrac, the file *fracSF.im* is the fluid/solid portion of the surface mesh and the file fracS.im is the Non-Solid/Fluid portion of the mesh. The final file that needs to be created by your favorite editor (emacs/vi..) is the input control deck file RocfracControl.txt, see Section 2.1.

#### 1.2.5 Run RocFrac

The program RocFrac is part of the GenX code, so it must be run under with in the GenX framework. In order to run it however in Stand-Alone mode (i.e. no other GenX modules are needed), the option 'SolidAlone Rocflo Rocfrac Rocburn' can be specified, thus allowing for a Rocfrac alone analysis problem. In order to run a stand alone problem, the pressure and burning rate needs to be applied within RocFrac since these quantities are not supplied from the Fluids or Burning modules. For this purpose, the subroutine RocFracInterfaceBuff in RocFracMain is used to specify these values. During the analysis the results output files are written to the Rocfrac/HDFout directory. These HDF files consist of: surface meshes results (isolid\_\*.hdf), volume meshes (solid\_\*hdf), and restart quantities (solid\_bnd\*.hdf). Note, as of this writing, for the restart, it must be restarted on the same number of processors for each run.

#### 1.2.6 Run the Post-processor

The isolid\_\*.hdf and solid\_\*.hdf files are used in Rocketeer to view the results. The solid\_bnd\*.hdf files are not to be used in Rocketeer, there're only used for restarting.

#### **1.3 File Management**

- *RocfracControl.txt* control deck input file. See Section 2.1 for a description of the control deck parameters. This file should be placed in the Rocfrac/ directory in the GenX tree.
- <prefix>.pat Patran Neutral File.
- <prefix>.neigh neighbor information file from the tetnhbor program.
- <prefix>/<prefix>.###.inp each processor's input file.

- *.res* output file, summarizes the input data from the control deck.
- HDFout/\*.hdf Rocketeer input and restart.

# **Executive Control Section**

This section describes the keywords and specifications for the input control deck file. The control deck file contains keyword statements that correspond to the analysis. The format definitions are as follows: A - character, F - real, I - integer. Keyword cards must begin with a \* in column 1. These keywords and keyword specifics are based on Abaqus's. For a more in-depth description the reader should consult the abaqus keyword manual.

#### 2.1 Executive System Parameters

#### 2.1.1 \*PREFIX: Define the prefix extension for IO files.

This option allows the user to specify what the prefix extensions are for the input files and the output files. The prefix should be no more then 20 characters in length. NOTE: ALWAYS NEEDED

Option Format	Entry
---------------	-------

First card:

1 A prefix name

#### 2.1.2 \*NRUN: Define the timing parameters\*\* (Obsolete)

This option is used to specify the parameters needed to obtain a stable solution. NOTE: ALWAYS NEEDED

Option	Format	Entry
--------	--------	-------

First card:

2 I divide the courant condition time step by

Note: typical values are 1.0-4.0 depending on whether ALE was specified.

#### **2.1.3** \*DYNAMIC:

This option is used to specify the parameters needed to obtain a stable solution. NOTE: ALWAYS NEEDED

#### **‡Optional Parameters:**

SCALE FACTOR

Factor to multiply the Courant limit, typical values are .8 - .9 without ALE and .5-.8 with ALE

First card: No cards

#### 2.1.4 \*ALE: Enable ALE

This option is used to run an ale simulation (the default is off if not specified).

Option Format Entry

First card:

2 I mesh motion stability parameter Note: typical values are between .1-.3

#### 2.1.5 \*IOPARAM: Output options

This option is used to specify the output interval to write results to a file that will later be post-processed. If the option is not given then the default is to never output the results to a file.

#### Option Format Entry

First card:

1 I time step interval for output

#### 2.1.6 \*IOFORMAT: Format of input files

This option is used to specify the format of the input file. If the value equals 1 then the input files are ASCII and if the value equals 0 then the input files are binary.

#### 2.1.7 \*POVIO: Output POV-RAY format

This option is used to specify that the outer boundary of the mesh should be written to a file for further analysis with the pov-ray ray tracing program. The output files need first to be run through the post pov-ray program. If the option is not given then the default is not to write any pov-ray files.

Option	Format	Entry
First card:		
1	F	value to magnify the displacement
2	Ι	time step to start the output
3	Ι	interval for output

#### 2.1.8 \*HYPERELASTIC: hyperelastic material model

Specifies a hyperelastic volumetric elements material model. **‡Optional Parameters:** 

NEOHOOKINC

Specifies the Incompressiable neo-Hookean model

ARRUDA-BOYCE

Specifies the ARRUDA-BOYCE material model, good for filled rubbers

Option	Format	Entry
First card:		
1	Ι	total number of materials
Following ca	rds:	
1	F	Young's Modulus
2	F	Poisson's Ratio
3	F	Density

#### 2.1.9 \*ELASTIC: hyperelastic material model

Specifies a elastic volumetric elements material model. **‡Optional Parameters:** 

NLGEOM

4

Specifies finite rotations

F

**Thermal Expansion Coefficient** 

#### 2.1. EXECUTIVE SYSTEM PARAMETERS

Option	Format	Entry
First card:		
1	Ι	total number of materials
Following ca	rds:	
1	F	Young's Modulus
2	F	Poisson's Ratio
3	F	Density
4	F	Thermal Expansion Coefficient

#### 2.1.10 \*MATVOL: Volumetric element material properties\*\* (Obsolete)

Specifies the volumetric elements material properties. NOTE: ALWAYS NEEDED

Option	Format	Entry
First car	d:	
1	Ι	total number of materials
Following	g cards:	
1	F	Young's Modulus
2	F	Poisson's Ratio
3	F	Density
4	F	Thermal Expansion Coefficient
5	F	Material type analysis
For card	5, the current o	ptions are:
0	- non-linear arr	ruda-boyce
1	- large deforma	tion, linear material
2	- small deforma	ation, linear material
-1	- Neo-Hookean	Incompressible
11	- Neo-Hookean	Incompressible, Node based formulation
13	- large deforma tion	tion, linear material, Node based formula-

#### **2.1.11** \*MATCOH: Cohesive element properties

Specifies the cohesive elements properties.

Option	Format	Entry
First card:		
1	Ι	total number of properties

Following cards:

1	F	Critical normal opening displacement
2	F	Critical tangential opening displacement
3	F	Critical tensial stress
4	F	Critical shearing stress
5	F	Initial Stress threshold

#### 2.1.12 \*PLOAD: Static Pressure Load

Defines the pressure value for a static pressure load on a triangular surface elements. Need a .press file to give a list of the surface triangles where the pressure is applied.

Option	Format	Entry	
First card:			
1	I	Pressure	

#### 2.1.13 \*PLOAD1: Dynamic Pressure Load

Specifies that the load changes with each time step, the pressure values are read in from an input file for each time step. The file name should be no longer then 20 characters.

Option Format Entry

First card:

1 A file name containing the nodal pressure values

#### 2.1.14 \*DUMMYTRACT: Assigns a traction when Rocfrac Stand alone is used

The magnitude of the traction force applied, the region that the traction gets applied to is specified in the RocFracUpdateInbuff subroutine.

Option	Format	Entry
First card:		
1	F	Traction magnitude value

#### 2.1.15 \*END: Denotes end of control deck input

Place at the end of the control deck input key variables. No options. NOTE: ALWAYS NEEDED

#### 2.1.16 \*BOUNDARY: Displacement Boundary Conditions

Specifies the meaning of the boundary condition flags set in the meshing program. A *zero* indicates that the boundary condition is an imposed velocity and a *one* is for an imposed force. Only the last three parameters should be changed to the specific value for each card. Note **\*BOUNDARY** is not used by the analysis code but only by the preprocessor, hence **\*BOUNDARY** should always be placed before the **\*END** option.

#### Option Format Entry

First to number of boundary flags:

10 0 0	3E	value x, value y, value z
$20\ 0\ 0$	3E	value x, value y, value z

#### 2.1.17 \*BOUNDARYMM: Mesh Motion Boundary Conditions

Specifies the meaning of the mesh motion boundary condition flags set in the meshing program. A *zero* indicates that the boundary condition is an imposed velocity and a *one* is for an imposed force.

#### Option Format Entry

First to number of boundary flags:

10 0 0	3E	value x, value y, value z
$20\ 0\ 0$	3E	value x, value y, value z

#### 2.1.18 \*ELEMENT: Element Type

Specifies the volumetric element type.

#### **‡Optional Parameters:**

V3D4

4 node tetrahedral

V3D4NCC

4 node tetrahedral, node based element, lumped using circumcenter  $% \left( {{{\left[ {{{\rm{T}}_{\rm{T}}} \right]}}} \right)$ 

V3D4N

4 node tetrahedral, node based element, lumped using centroid

V3D10R

10 node tetrahedral, reduced integration

V3D10

10 node tetrahedral

# Three-dimensional solid element library

This section defines the three-dimensional solid (continuum) elements available in RocFrac.

#### **3.1 Volumetric Stress/Displacement Elements:**

- V3D4 4-node linear tetrahedron
- V3D10 10-node quadratic tetrahedron

Warning: Element type **C3D4** is a constant stress tetrahedron. This element only provides accurate results in general cases with very fine meshing.

#### Active degrees of freedom:

1, 2, 3  $(u_x, u_y, u_z)$ 

#### **3.2** Cohesive Stress/Displacement Elements:

- **C3D6** 6-node linear triangular prism with 3-point gauss integration.
- C3D12 12-node quadratic triangular prism (NOT YET IMPLEMENTED)

#### Active degrees of freedom:

1, 2, 3 ( $\Delta u_x, \Delta u_y, \Delta u_z$ )



Figure 3.1: Node ordering and face numbering for tetrahedral elements



Figure 3.2: Node ordering for cohesive elements

# **RocFrac Input File**

The Input Files ( i.e. the <prefix>/<prefix>.N#.inp files, where N# is the processors id) are used to communicate the analysis model into Rocfrac. Each processor has its own input file.

#### 4.1 Data Format

The input files format is as follows:

#### Packet 01: Version Number

Data Card 1

VERS

VERS = Version Number of Analysis Code

#### Packet 02: Node Data

Data Card 1

N1, Aux, Aux, Aux, Aux

N1 = Number of Nodes Aux = Auxillary flags (not applicable)

Data Card 2 (Repeted N1 times)

ID	Х	Y	NDFLAG1
	X	X = X	Cartesian Coordinate of Node
	Y	X = Y	Cartesian Coordinate of Node
	Z	; = 2 C	artesian Coordinate of Node
	N	IFLAG	1 = Generic Flag of Node (not applicable)

#### Packet 03: Structural Boundary Conditions

Data Card 1

NumBC, AuxFlag

NumBC = Number of Boundary Condition Flags AuxFlag = Auxillary Flag (not applicable)

Data Card 2 (Repeated NumBC times)

NodeID	BCFLAG1	BCFLAG2
	NodeID = Node BCFLAG1 = Bo BCFLAG2 = Bo	Identification oundary Condition Flag 1 oundary Condition Flag 2 (not applicable)

#### Packet 04: Mesh Motion Boundary Conditions

Data Card 1

NumBC, AuxFlag

NumBC = Number of Boundary Condition Flags AuxFlag = Auxillary Flag (not applicable)

Data Card 2

NodeID BCFLAG1 BCFLAG2 NodeID = Node Identification BCFLAG1 = Boundary Condition Flag 1 BCFLAG2 = Boundary Condition Flag 2 (not applicable)

#### Packet 05: Element Data

#### Data Card 1

л, пол
nts (Mate-
rder Ele-

#### Data Card 2

IMAT, LND, AUX, AUX
IMAT = Material ID
LND = Element corner nodes followed by additional nodes
NumElTot = Number of Elements Total
AUX = Auxillary Input (not applicable)
AUX = Auxillary Input (not applicable)

#### Packet 06: Parallel Communciation

Data Card 1

NumNeigh

NumNeigh = Number of Neighboring Processors

Data Card 2 (Repeated NumNeigh times)

NeighID,NumNodeShare

NeighID = Neighbor's ID NumNodeShare = Number of Shared Nodes with NeighID

Data Card 3 (Repeated NumNodeShare times)

NodeShareID

NodeShareID = ID of shared node

#### Packet Type 99:

Data Card 1

99

Signals End of Input File

# **Example Problems**

#### 5.1 Layered Two Material Cantilever Beam

This example is of a cantilever beam composed of two materials. The top half of the beam is composed of a rubber and the bottom half steel, shown in Figure 5.1. The rubber has a Young's Modulus of 0.991 GPa, Poisson's ratio of .46, Density of 956.0 kg/m^3 and is to be modeled using the NeoHookean Incompressible material model. The steel has a Young's Modulus of 210 GPa, Poisson's ratio of .27, density = 7870.9 kg/m^3 and is to be modeled using small displacements and linear material response. The traction load is 100.0 and the points are all fixed at the wall.



Figure 5.1: Geometry and loading condition

The input files for a four processor run can be found in cvs at /CSAR/brtnfld/GenXData/Beam2Mat.